

# Modern C++ Programming

## 3. BASIC CONCEPTS II

---

*Federico Busato*

University of Verona, Dept. of Computer Science  
2018, v1.0



# Agenda

## ■ Memory Management: Heap and Stack

- Heap allocation and memory leak
- Stack memory
- Stack 2D allocation
- Initialization
- Data/Bss memory segment

## ■ Storage Class Specifiers

## ■ Pointers and References

- Pointers
- Void Pointer
- Address-of Operator
- Pointer Arithmetic
- Reference

## ■ sizeof Operator

## ■ Other Keywords

- const, constexpr
- volatile
- using, decltype

## ■ Explicit Type Conversion

## ■ Declaration and Definition

## ■ Functions

- Call-by-value/pointer/reference
- inline
- Default parameters
- Overloading

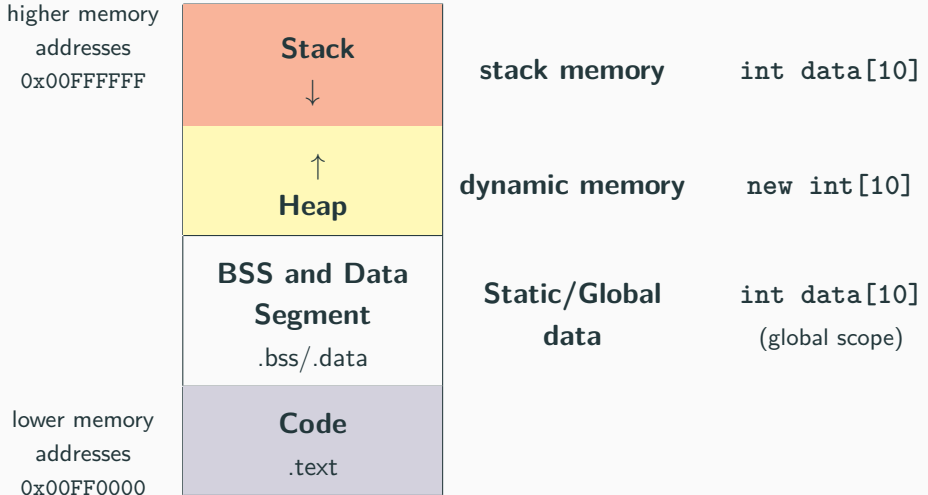
## ■ Unions and Bitfields

## ■ Preprocessing

- Macro
- Pragma

# Memory Management: Heap and Stack

---



## Dynamic allocation on **heap** in C:

```
int* value = (int*) malloc(sizeof(int));           // allocate one int
int* array1 = (int*) malloc(10 * sizeof(int));     // allocate ten int
int* array2 = (int*) calloc(10 * sizeof(int));     // allocate ten int
                                                    // and set to 0
free(array1); // free is the C method applied to deallocate memory
```

The C++ operator `new` is applied to allocate a variable/object/etc. in heap memory:

```
int* value = new int;           // allocate one int
int* array1 = new int[10];      // allocate ten int
int* array2 = new int[10]();    // allocate ten int and set to 0
delete value;                  // delete is the C++ operator applied to deallocate
delete[] array1;
```

Note. For an array of objects:

- `delete/delete[]` recursively invoke destructor (see next lectures)
- `delete/delete[]` applied to `nullptr` has no effect (safe)

## Definition (Memory Leak)

Dynamically allocated entity in heap memory is no longer used by the program, but still maintained overall its execution

An object is stored in memory but cannot be accessed by the running code

Problems:

- Illegal memory accesses
- Undefined values
- Additional memory consumption

## Fundamental rules:

- Each object allocated with `new` must be deallocated with `delete`
- Each object allocated with `new[]` must be deallocated with `delete[]`

## Common errors:

Pointer loss and wild pointer:

```
int main() {  
    int* array = new int[10];  
    array      = nullptr; // memory leak!! array cannot be deallocated!  
    new int[10];           // legal code but memory leak!!  
    int* ptr;              // wild pointer: Where will this pointer points?  
    ...  
}
```

Double delete:

```
int* array = new int[10];  
delete[] array; // ok -> array: dangling pointer  
delete[] array; // double free or corruption!!  
// program aborted
```

Unless it is allocated in heap memory (i.e. `new`), then it is either in stack memory or CPU registers

**Important:**

**Every object which resides in the stack is not valid outside the current scope!!**

```
int* wrongFunction() {  
    int A[3] = {1, 2, 3};  
    return A;  
}  
  
int main() {  
    int* ptr = wrongFunction();  
    cout << ptr[0]; // Illegal memory access!!  
}
```

**Important:**

The organization of stack memory enables much higher performance. On the other hand, this memory space is **limited!!**

It is  $\approx 8MB$  on linux by default.

`sizeof` and memory allocation:

```
int A[10];  
int* B = new int[10];  
cout << sizeof(A); // print sizeof(int) * 10 = 40  
cout << sizeof(B); // print sizeof(int*) = 8 (64-bit)
```

```
int* ptr[10]; // array of ten integer pointers  
              // read as (int*) ptr[10]  
int (*ptr)[10]; // pointer to an array of ten integer  
                // equal to:  
                //     int a[10];  
                //     int* ptr = a;
```

Easy on stack:

```
int A[3][4];
```

Dynamic Memory 2D allocation/free:

```
int* A = new int*[3];  
for (int i = 0; i < 3; i++)  
    A[i] = new int[4];  
  
for (int i = 0; i < 3; i++)  
    delete[] A[i];  
delete[] A;
```

Dynamic memory 2D allocation/free C++11:

```
auto A = new int[3][4];    // allocate 3 objects of size int[4]  
int n = 3;                // dynamic value  
auto B = new int[n][4];    // ok  
// auto C = new int[n][n]; // compile error  
delete[] A;                // same for B, C
```

# Memory Management (Stack Array Initialization)

One dimension:

```
int A[3] = {1, 2, 3}; // explicit size
int B[] = {1, 2, 3}; // implicit size
char C[] = "abcd";    // implicit size
int C[3] = {1, 2};    // C[2] has undefined value
int D[4] = {0}; // all values of D are initialized to 0
int E[3] = {}; // all values of E are initialized to 0 (C++11)
```

Two dimensions:

```
// int F[][] = ...; // compile error
// int G[2][] = ...; // compile error
int G[][2] = { {1,2}, {3,4}, {5,6} }; // ok
int H[2][2] = { 1, 2, 3, 4 }; // ok
```

# Memory Management (Data and BSS Segment)

```
int data[] = {1, 2, 3, 4}; // data segment memory
int big_data[1000000] = {}; // bss segment memory (zero-initialized)

int main() {
    int A[] = {1, 2, 3}; // stack memory
}
```

Data/Bss (Block Started by Symbol) are larger than stack memory (max  $\approx$  1GB in general) but slower

# Default Initialization

---

## Rules:

- An object with **dynamic** (heap) storage duration has indeterminate value
- An object whose initializer is an **empty set of parentheses** is zero or default initialized
- Objects with **static** or **thread storage** duration are zero or default initialized

# Initialization

```
int a1;                // indeterminate
int* a2 = new int;      // indeterminate
int* a3 = new int();    // indeterminate
int* a4 = new int(4);   // allocate a single value equal to 4!!

int* b1 = new int[4](); // allocate 4 elements zero-initiliazed
int* b2 = new int[4]{}; // indeterminate
int* b3 = new int[4]{1, 2}; // set first, second, indeterminate
                               // other values

int c1(4);              // c1 = 4;
int c2 = int();         // zero-initiliazed
int c3(0);              // zero-initiliazed
int c4 { 0 };           // zero-initiliazed
int c5 = { 0 };         // zero-initiliazed

static int d1;          // zero-initiliazed
thread_local int d2;    // zero-initiliazed
// int d3();            // d3 is a function
```

# Pointers and References

---

# Pointers and Pointer Dereferencing

## Definition (Pointer)

A pointer is a value referring to a location in memory

## Definition (Pointer Dereferencing)

Pointer dereferencing means obtaining the value stored in at the location referred to the pointer

```
int* ptr1 = new int;  
*ptr1     = 4;      // dereferencing (assignment)  
int a     = *ptr1;  // dereferencing (get value)
```

Common errors:

```
int *ptr1, ptr2; // one pointer and one integer!!  
int *ptr1, *ptr2; // ok two pointers
```

## void Pointer (Generic Pointer)

Instead of declaring different types of pointer variable it is possible to declare single pointer variable which can act as any pointer types

- A `void*` can be assigned to another `void*`
- `void*` can be compared for equality and inequality
- A `void*` can be explicitly converted to another type.
- Other operations would be unsafe because the compiler cannot know what kind of object is really pointed to. Consequently, other operations result in compile-time errors

```
cout << (sizeof(void*) == sizeof(int*)); // print true

int array[] = { 2, 3, 4 };
void* ptr = array;
cout << *array;           // print 2
// cout << *ptr;          // compile error
cout << *((int*) ptr);    // print 2
// void* ptr2 = ptr + 2;  // compile error
```

# Address-of operator &

The **address-of operator** (&) returns the address of the variable

```
int a = 3;
int* b = &a; // address-of operator,
             // 'b' is equal to the address of 'a'

a++;
cout << *b; // print 4;

int array[4]; // &array is a pointer to a array of size 4
int size1 = (&array)[1] - array;
int size2 = *(&array + 1) - array;
cout << size1; // print 4
cout << size2; // print 4
```

To not confuse with **Reference syntax**: `T& var = ...`

# 1 + 1 ≠ 2 : Pointer Arithmetic

## Pointer syntax:

`ptr[i]` is equal to `*(ptr + i)`

## Pointer arithmetic rule:

`address(ptr + i) = address(ptr) + (sizeof(T) * i)`

where T is the type of elements pointed by ptr

## Example:

```
int array[4] = {1, 2, 3, 4};  
cout << array[1];           // print 2  
cout << *(array + 1);       // print 2  
cout << array;               // print 0xFFFFAFF2  
cout << array + 1;          // print 0xFFFFAFF6!!
```

```
char arr[3] = "abc"
```

value	address	
'a'	0x0	←arr[0]
'b'	0x1	←arr[1]
'c'	0x2	←arr[2]

```
int arr[3] = {4,5,6}
```

value	address	
4	0x0	←arr[0]
	0x1	
	0x2	
	0x3	
5	4	←arr[1]
	0x5	
	0x6	
	0x7	
	0x8	←arr[2]

## Definition (Reference)

A variable **reference** is an **alias**, namely another name for an already existing variable. Both variable and variable reference can be applied to refer the value of the variable

References are safer than pointers:

- References **cannot have NULL** value. You must always be able to assume that a reference is connected to a legitimate piece of storage.
- References **cannot be changed**. Once a reference is initialized to an object, it cannot be changed to refer to another object.  
(Pointers can be pointed to another object at any time)
- References must be **initialized** when it is created.  
(Pointers can be initialized at any time)
- A pointer has its own memory address and size on the stack, reference shares the **same memory address** (with the original variable) but also takes up some space on the stack.

# Reference (Examples)

Reference syntax: `T& var = ...`

```
//int& d;    // reference. compile error!! no initialization
int  c = 2;
int& e = c;  // reference. ok valid initialization
e++;        // increment `e'
cout << c;  // print 3
```

```
int* b = &a; // pointer
int* c = &a; // pointer
b++;        // change the value of the pointer `b'
*c++;       // change the value `a'

int& c = a;  // reference
c++;        // change the value `a'
```

## References (Function Arguments)

Reference vs. pointer arguments:

```
void f(int* value) {} // value may be a nullptr
void g(int& value) {} // value is never a nullptr

int a = 3;
f(&a); // ok
g(a); // ok
//g(3); // compile error "3" is not a reference of something
```

References can be use to indicate fixed size arrays:

```
f(int (&array)[3]) {} // accepts only arrays of size 3

int A[3], B[4];
int* C = A;

f(A); // ok
f(B); // compile error!! B has size 4
f(C); // compile error!! C is a pointer
```

## References (Arrays)

```
int A[4];  
int (&B)[4] = A;      // ok  
int C[10][3];  
int (&D)[10][3] = C; // ok  
  
auto c = new int[3][4]; // type is int (*)[4]  
// read as "pointer to arrays of 4 int"  
// int (&d)[3][4] = c;    // compile error  
// int (*e)[3]      = c;  // compiler error  
int (*f)[4] = c;         // ok
```

Reference:

[1] [www3.ntu.edu.sg/home/ehchua/programming/cpp/cp4\\_PointerReference.html](http://www3.ntu.edu.sg/home/ehchua/programming/cpp/cp4_PointerReference.html)

## References and struct

- The dot (.) operator is applied to local objects and references
- The arrow operator (->) is used with a pointer to an object

```
struct A {  
    int x = 3;  
};  
  
A obj;  
  
A* p = &obj; // pointer  
p->x; // arrow syntax  
  
A& ref = obj; // reference  
std::cout << obj.x; // dot syntax  
std::cout << ref.x; // dot syntax
```

# sizeof Operator

---

The `sizeof` is a compile-time operator that determines the size, in bytes, of a variable or data type

- `sizeof` returns a value of type `size_t`
- `sizeof` (incomplete type) produces compile error
- `sizeof` (bitfield) produces compile error
- `sizeof` (anything) never returns 0 except for array of size 0
- `sizeof(char)` always returns 1
- When applied to structures it also takes into account padding
- When applied to a reference, the result is the size of the referenced type

```
sizeof(int);           // 4
sizeof(int*);          // 8 in a 64-bit OS
sizeof(void*)          // 8 in a 64-bit OS
sizeof(size_t)         // 8 in a 64-bit OS

char a;
char& b = a;
sizeof(&a);             // 8 in a 64-bit OS (pointer)
sizeof(b);              // 1 sizeof(char)

struct A {};
sizeof(A);              // 1 : sizeof never return 0

A array1[10];
sizeof(array1);         // 1 : array of empty structures

int array2[0];
sizeof(array2);         // 0
```

```
struct B {  
    int x;  
    char y;  
};  
  
struct C : B { // C extends B  
    short z;  
};  
  
sizeof(B);      // 8 : 4 + 1 (+ 3) (padding)  
sizeof(C);      // 12 : sizeof(B) + 2 (+ 2) (padding)  
  
int array[4]  
sizeof(array)   // 16: 4 elements of 4 bytes  
sizeof(array) / sizeof(int); // 4 elements
```

# Other C++ Keywords

---

**Definition (const keyword)**

It indicates objects never changing value after their initialization (they must be initialized when declared)

Evaluated at compile-time

```
int size = 3;
int A[size] = {1, 2, 3}; // Technically possible (size is dynamic)
                        // But NOT approved by the C++ standard.

const int SIZE = 3;
// SIZE = 4;           // compile error!!
int B[SIZE] = {1, 2, 3}; // ok

const int size2 = size;
int B[size2] = {1, 2, 3}; // BAD programming!! size is not const
// (some compilers allow variable size stack array -> dangerous!!)
```

## Constness rules:

- `int* → const int*`
- `const int* ↗ int*`

```
int g(const int* array) { // the values of array cannot be  
    ... // modified  
}
```

```
void f(const int) { // pass-by-value combined with 'const'  
    ... // note: it is not useful because the value  
} // is copied
```

- `int*` pointer to int
  - The value of the pointer can be modified
  - The elements refereed by the pointer can be modified
- `const int*` pointer to const int. Read as `(const int)*`
  - The value of the pointer can be modified
  - The elements refereed by the pointer cannot be modified
- `int *const` const pointer to int
  - The value of the pointer cannot be modified
  - The elements refereed by the pointer can be modified
- `const int *const` const pointer to const int
  - The value of the pointer cannot be modified
  - The elements refereed by the pointer cannot be modified

Note: `const int *` is equal to `int const*`

Tip: pointer types should be read from right to left

# constexpr keyword

## Definition (constexpr)

C++11 guarantees compile-time evaluation of an expression as long as all its arguments are constant

- `const` guarantees the value of a variable to be fixed overall the execution of the program
- `constexpr` tells the compiler that the expression results is at compile-time. `constexpr` value implies `const` for variables
- C++11: `constexpr` must contain exactly one `return` statement and it must not contain loops or switch
- C++14: `constexpr` has no restrictions

```
constexpr int square(int value) {  
    return value * value;  
}  
  
const int v1 = square(3); // compile-time evaluation  
int a = 3;  
const int v2 = square(a); // run-time evaluation
```

## Type Alias Keyword (`using` and `decltype`)

- In C++11, the `using` keyword has the same semantics of `typedef` specifier (alias-declaration), but with better syntax

```
typedef int distance_t; // equal to:  
using distance_t = int;
```

- In C++11, `decltype` captures the type of an object or an expression

```
int a = 3;  
decltype(a) b = 5;           // 'b' is int  
decltype(2.0f) c = 3.0f;     // 'c' is float  
decltype(a + 2.0f) d = 3.0f; // 'd' is float  
decltype(f(a)) e = ...;      // 'e' depends on f(a)
```

# Explicit Type Conversion

---

Old style cast `(type) value`

C++11 cast:

- `static_cast` does compile-time, not run-time checking of the types involved. In many situations, this can make it the safest type of cast, as it provides the least room for accidental/unsafe conversions between various types.
- `reinterpret_cast`  
`reinterpret_cast<T*>(v)` equal to `(T*) v`  
`reinterpret_cast<T&>(v)` equal to `*((T*) &v)`
- `const_cast` may be used to cast away (remove) constness or volatility.

## Static cast vs. old style cast:

```
char a[] = {1, 2, 3, 4};  
int* b = (int*) a; // ok  
cout << b[0];      // print 67305985 not 1!!  
int* c = static_cast<int*>(a); // compile error!! unsafe conversion
```

## Const cast:

```
const int a = 5;  
const_cast<int>(a) = 3; // ok
```

## Reinterpret cast: (bit-level conversion)

```
float b = 3.0f;  
// bit representation of b: 01000000010000000000000000000000  
int c = reinterpret_cast<int>(b);  
// bit representation of c: 01000000010000000000000000000000  
int a[3][4]; // array reshaping example  
int (&b)[2][6] = reinterpret_cast<int (&)[2][6]>(a);  
int (*c)[6] = reinterpret_cast<int (*)[6]>(a);
```

# Narrowing Conversion

C++11 provides protection against **narrowing**, i.e. it against assigning a numeric value to a numeric type not capable of holding that value

```
int main() {  
    int a1 = 36.6;      // ok  
    // int a2 = { 36.6 }; // compile error  
  
    float b1 = 36.6;    // ok  
    // float b2 = 36.6;  // compile error  
  
    char c1 = 512;      // ok  
    // char c2 = { 512 }; // compile error  
}
```

# Declaration and Definition

---

## Definition (declaration/prototype)

A **declaration** (or prototype) of an entity is an identifier describing its type

A declaration is what the compiler and the linker needs to accept references to that identifier

## Definition (definition/implementation)

An entity **definition** is the implementation of a declaration

## Declaration/Definition (incomplete type)

A declaration without a concrete implementation is an incomplete type (as void)

C++ Entities (class, functions, etc.) can be declared multiple times (with the same signature)

```
struct A;    // declaration 1
struct A;    // declaration 2 (ok)

struct B {   // declaration and definition
    int b;
// A x;    // incomplete type
};

struct A {   // definition
    char c;
}
```

# Functions

---

## Definition (Signature)

Type signature defines the inputs and outputs for a function. A type signature includes the number of arguments, the types of arguments and the order of the arguments contained by a function

## Definition (Function Parameter [formal])

A parameter is the variable which is part of the method's signature

## Definition (Function Argument [actual])

An argument is the actual value (instance) of the variable that gets passed to the function

```
int f(int a, char* b); // function declaration
                        // signature: (int, char*)
                        // parameters: int a, char* b

int f(int a, char*) { // function definition
    ...              // b can be omitted if not used
}

// char f(int a, char* b); // compile error!! same signature

// int f(const int a, char* b); // invalid declaration!
                                // const int == int
int f(int a, const char* b);    // ok

int main() {
    f(3, "abc"); // function arguments: 3, "abc"
                // error: "f" call f(int, const char*)
                // which is not defined
}
```

# Call-by-Value

## Definition (Call-by-value)

Values are copied and assigned to input arguments of the method

### Advantages:

- Changes made to the parameter inside the function have no effect on the argument

### Disadvantages:

- Performance penalty if the copied arguments are large (e.g. a structure with a large array)

### When to use:

- Small objects that do not need to be change

### When not to use:

- Arrays: arrays decay into pointers, when passed to a function
- Large objects

# Call-by-Pointer

## Definition (Call-by-pointer)

The addresses of variables are copied and assigned to input arguments of the method

Inside the function, the address is used to access the actual argument used in the call

### Advantages:

- Allows a function to change the value of the argument
- Copy of the argument is not made (fast)

### Disadvantages:

- The argument may be `null`
- Dereferencing a pointer is slower than accessing a value directly

### When to use:

- When passing built-in arrays (use `const` if read-only)

### When not to use:

- Small objects

# Call-by-Reference

## Definition (Call-by-reference)

The reference of variables are copies and assigned to input arguments of the method

### Advantages:

- Allows a function to change the value of the argument
- Copy of the argument is not made (fast)
- References must be initialized (no null pointer)
- Avoid implicit conversion

### When to use:

- Structs or Classes (use `const` if read-only)

# Examples

```
struct MyStruct {  
    int field;  
};  
  
void f1(int a);           // call by value  
void f2(int& a);          // call by reference  
void f3(const int& a);    // call by const reference  
void f4(MyStruct& a);     // requires a.field to access  
  
void f5(int* a);          // call by pointer  
void f6(const int* a);    // call by const pointer  
void f7(MyStruct* a);     // requires a->field to access  
//-----  
char c = 'a';  
f1('a');    // ok, pass-by-value  
// f2('a'); // compile error!! pass-by-reference
```

# inline Function Declaration

## Definition (inline)

`inline` specifier is a hint for the compiler. The code of the function can be copied where it is called (inlining)

```
inline void f(int a) { ... }
```

- It is just a hint. The compiler can ignore the hint ( `inline` increases the compiler heuristic threshold)
- The compiled code is larger because the `inline` function is expanded in-place for every function call

GCC/Clang extensions allow to force inline functions:

```
inline __attribute__((always_inline)) void f(int a) { ... }
```

# Function Default Parameters

## Definition (Default/Optional parameter)

A **default parameter** is a function parameter that has a default value provided to it.

If the user does not supply a value for this parameter, the default value will be used. If the user does supply a value for the default parameter, the user-supplied value is used instead of the default value

- All default parameters must be the rightmost parameters
- Default parameters can only be declared once
- Default parameters can improve compile time because they avoid defining other overloaded functions

```
void f(int a, int b = 20);  
// void g(int a = 10, int b); // compile error  
  
void f(int a, int b) { ... } // default value of "b" already set  
  
int main() {  
    f(5); // b is 20  
}
```

# Function Overloading (Ambiguous Matches)

An **overloaded declaration** is a declaration with the same name as a previously declared identifier (in the same scope), except that both declarations have different arguments and different definition (implementation)

## Overload resolution rules:

- An exact match
- A promotion (e.g. char to int)
- A standard type conversion (e.g. between float and int)
- A constructor or user-defined type conversion

```
void f(int a);  
void f(float value);  
  
void g(int a);  
  
void h(int a);  
void h(int a, int b = 0);
```

```
f(0);    // ok  
// f('a'); // ambiguous matches, compile error  
f(2.3f); // ok  
// f(2.3); // ambiguous matches, compile error  
  
g(2.3);  // ok, standard type conversion  
  
// h(3);  // ambiguous matches, compile error
```

# Functor (Function as Argument)

## Definition (Functor)

**Functors**, or **function object**, are objects that can be treated as parameters

Function type:

`<return_type>(*[function_name])(<arg_type1>, <arg_type2>, ...)`

```
int eval(int a, int b, int (*f)(int, int)) {  
    return f(a, b);  
}  
  
int add(int a, int b) { //type: int (*)(int, int)  
    return a + b;  
}  
  
int sub(int a, int b) {  
    return a - b;  
}
```

```
cout << eval(4, 3, add); // print 7  
cout << eval(4, 3, sub); // print 1
```

# Union and Bitfield

---

## Definition (Union)

A **unions** is a special data type that allows to store different data types in the same memory location

- The **union** is only as big as necessary to hold its largest data member
- The **union** is a kind of “overlapping” storage

```
union A {  
    int x;  
    char y;  
}; // sizeof(A): 4  
  
A a;  
a.x = 1023; // bits: 00..0111111111  
a.y = 0; // bits: 00..0110000000  
std::cout << a.x; // print 512 + 256 = 768
```

## Definition (Bitfield)

A bitfield is variable of a structure with a predefined bit width.

A bitfield can hold bits instead byte

```
struct S1 {  
    int b1 : 10;    // range [0, 1023]  
    int b2 : 10;    // range [0, 1023]  
    int b3 : 8;     // range [0, 255]  
};  
  
struct S2 {  
    int b1 : 10;  
    int    : 0;     // force start at bit 32  
    int b2 : 10;  
};
```

# Preprocessing

---

## Preprocessor macros are evil:

### Do not use macro expansion!!

...or use as little as possible

- Macros can't be debugged
- Macro expansions can have strange side effects
- Macros have no namespace or scope

Preprocessor Macros:

- `#if <condition>, #elif <condition>, #else, #endif`
- `#if defined(...)` equal to `#ifdef ...`
- `#if !defined(...)` equal to `#ifndef ...`
- `#define <macro>` multi lines \
- `#undef <macro>` (every macro should be undefined for safety reasons)

## Commonly useful macros:

- `__LINE__` Integer value representing the current line in the source code file being compiled
- `__FILE__` A string literal containing the presumed name of the source file being compiled
- `__DATE__` A string literal in the form "MMM DD YYYY" containing the date in which the compilation process began
- `__TIME__` A string literal in the form "hh:mm:ss" containing the time at which the compilation process began

- **Select code depending on the C/C++ version**

- `#if defined(__cplusplus)` C++ code
- `#if __cplusplus == 199711L` ISO C++ 1998/2003
- `#if __cplusplus == 201103L` ISO C++ 2011

- **Select code depending on the compiler**

- `#if defined(__GNUG__)` The compiler is gcc/g++
- `#if defined(__clang__)` The compiler is clang/clang++

- **Select code depending on the operation system or environment**

- `#if defined(_WIN64)` OS is Windows 64-bit
- `#if defined(__linux__)` OS is Linux
- `#if defined(__APPLE__)` OS is Mac OS
- `#if defined(__MINGW32__)` OS is MinGW 32-bit
- ...and many others

## Do not define macro in header file and before includes!!

Example:

```
#include <iostream>

#define value    // very dangerous!!
#include <big_lib>
using namespace std;

int main() {
    cout << f(4); // should print 7, but it prints always 3
}
```

big\_lib.hpp:

```
int f(int value) { // 'value' disappear
    return value + 3;
}
```

## Use parenthesis in macro definition!!

Example:

```
#include <iostream>
using namespace std;

#define SUB1(a, b)  a - b           // wrong
#define SUB2(a, b) (a - b)         // wrong
#define SUB3(a, b) ((a) - (b))     // correct

int main() {
    cout << (5 * SUB1(2, 1)); // print 9 not 5!!
    cout << SUB2(3+3, 2+2);   // print 6 not 2!!
    cout << SUB3(3+3, 2+2);   // print 2
}
```

## Macro make hard to find compile errors!!

Example:

```
1: #include <iostream>
2: using namespace std;
3:
4: #define F(a) {      \
5:     ...             \
6:     ...             \
7:     return v;
8:
9: int main() {
10:     F(3);    // compile error at line 5!!
11: }
```

- In which line is the error??!

In **C++11**, a **variadic macro** is a special macro accepting a varying number of arguments (separated by comma)

Each occurrence of the special identifier `__VA_ARGS__` in the macro replacement list is replaced by the passed arguments

Example:

```
#define PRINT3(...) \  
printf("list: %d %d %d\n", __VA_ARGS__);  
  
#define PRINT4(...) \  
printf("list: %d %d %d %d\n", __VA_ARGS__);  
  
PRINT3(1, 2, 3)  
PRINT4(1, 2, 3, 4)
```

When macros are necessary:

- **Conditional compiling:** different architectures, compiler features, etc.
- **Mixing different languages:** code generation (example: asm assembly)
- **Complex name replacing:** see template programming

**Otherwise**, prefer `const` and `constexpr`, specially for constant values and functions

```
#define SIZE 3 // replaced with
const int SIZE = 3;

#define SUB(a, b) ((a) - (b)) // replaced with
constexpr int sub(int a, int b) {
    return a - b;
}
```

Most important pragmas:

- `#pragma once` In C++11, it indicates that a (header) file is only to be parsed once, even if it is (directly or indirectly) included multiple times in the same source file.

It is an alternative of the standard include guard:

```
#ifndef FILENAME_H
#define FILENAME_H
...code...
#endif /* FILENAME_H */
```

- `#pragma unroll` Applied immediately before a for loop, it replicates his body to eliminates branches. Unrolling enables aggressive instruction scheduling (supported by Intel/Ibm/Clang compilers).
- `#pragma message "text"` Display informational messages at compile time. (every time this instruction is compiled).

- `_Pragma(<command>)` (C++11)

It is an operator (like `sizeof`), and can be embedded in a macro (ex. `#define`)

```
#define MY_LOOP \
    _Pragma(unroll) \
    for(i=0;i<10;i++) \
        cout<<"c";
```

- `#error "text"` The directive emits a user-specified error message at compile time when the compiler parse the related instruction.

Find the size offset of a field inside a structure:

```
#define FIELD_OFFSET(structure, field) \
    reinterpret_cast<size_t>(\
        &((reinterpret_cast<structure*>(0))->field) )
```

Get the size of an arbitrary type without using `sizeof`

```
#define MY_SIZE(type, ret) \
    { type x; ret = reinterpret_cast<char*>(&x + 1) - \
        reinterpret_cast<char*>(&x); }
```

```
struct A {\
    int    a;\
    float b;\
};
```

```
std::cout << FIELD_OFFSET(A, b); // print 4
int size;
MY_SIZE(A, size); // size = 8
```